|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Scenario** | **Movement** | **AM Peak Hour** | | | | **PM Peak Hour** | | | | **Saturday Peak Hour** | | | |
| **v/c** | **LOS** | **Delay**  *(s/veh)* | **95th %ile**  **queue** *(m)* | **v/c** | **LOS** | **Delay**  *(s/veh)* | **95th %ile**  **queue** *(m)* | **v/c** | **LOS** | **Delay**  *(s/veh)* | **95th %ile**  **queue** *(m)* |
| Existing | EBTLR WBL WBTR NBL NBTR SBL SBTR | 0.02 0.06 0.02 0.05 0.35 0.03 0.50 | A D A A A A A | 0.3 53.7 0.2 1.6 0.9 1.2 2.1 | 0 7 0 0 11 1 56 | 0.09 0.33 0.12 0.01 0.62 0.20 0.45 | A E A A A A A | 1.2 71.2 1.2 1.3 1.9 1.7 1.0 | 0 19 0 0 17 1 14 | 0.02 0.56 0.19 0.01 0.62 0.19 0.59 | A E A A A A A | 0.2 58.3 1.3 1.5 2.6 2.0 1.8 | 0 34 0 0 10 2 21 |
| **Overall** | **—** | A | 1.7 | **—** | **—** | A | 2.2 | **—** | **—** | A | 3.8 | **—** |
| 2026 Future Background | EBTLR WBL WBTR NBL NBTR SBL SBTR | 0.02 0.06 0.02 0.05 0.37 0.03 0.53 | A D A A A A A | 0.3 53.7 0.2 1.6 0.9 1.3 2.3 | 0 7 0 0 11 1 59 | 0.09 0.33 0.13 0.02 0.65 0.21 0.48 | A E A A A A A | 1.2 71.2 1.2 1.3 2.3 2.3 1.1 | 0 19 0 0 16 1 15 | 0.02 0.56 0.19 0.02 0.65 0.20 0.61 | A E A A A A A | 0.2 58.3 1.3 1.5 2.7 2.1 1.9 | 0 34 0 0 11 2 22 |
| **Overall** | **—** | A | 1.8 | **—** | **—** | A | 2.4 | **—** | **—** | A | 3.8 | **—** |
| 2026 Total Future | EBTLR WBL WBTR NBL NBTR SBL SBTR | 0.02 0.06 0.02 0.06 0.38 0.03 0.53 | A D A A A A A | 0.3 53.7 0.2 1.6 0.9 1.3 2.3 | 0 7 0 0 11 1 60 | 0.09 0.33 0.13 0.02 0.66 0.22 0.49 | A E A A A A A | 1.2 71.2 1.3 1.7 2.4 2.8 1.1 | 0 19 0 0 17 1 16 | 0.02 0.56 0.19 0.02 0.67 0.21 0.63 | A E A A A A A | 0.2 58.3 1.3 1.5 2.8 2.3 2.1 | 0 34 0 0 11 2 24 |
| **Overall** | **—** | A | 1.9 | **—** | **—** | A | 2.4 | **—** | **—** | A | 3.9 | **—** |
| Total Future | Move0  Move1  Move2  Move3  Move4  Move5  Move6  Move7  Move8  Move9  Move10  Move11 | V0  V1  V2  V3  V4  V5  V6  V7  V8  V9  V10  V11 | L0  L1  L2  L3  L4  L5  L6  L7  L8  L9  L10  L11 | D0  D1  D2  D3  D4  D5  D6  D7  D8  D9  D10  D11 | Q0  Q1  Q2  Q3  Q4  Q5  Q6  Q7  Q8  Q9  Q10  Q11 | V0  V1  V2  V3  V4  V5  V6  V7  V8  V9  V10  V11 | L0  L1  L2  L3  L4  L5  L6  L7  L8  L9  L10  L11 | D0  D1  D2  D3  D4  D5  D6  D7  D8  D9  D10  D11 | Q0  Q1  Q2  Q3  Q4  Q5  Q6  Q7  Q8  Q9  Q10  Q11 | V0  V1  V2  V3  V4  V5  V6  V7  V8  V9  V10  V11 | L0  L1  L2  L3  L4  L5  L6  L7  L8  L9  L10  L11 | D0  D1  D2  D3  D4  D5  D6  D7  D8  D9  D10  D11 | Q0  Q1  Q2  Q3  Q4  Q5  Q6  Q7  Q8  Q9  Q10  Q11 |
| **Overall** | **—** | **LO** | **DO** | **—** | **—** | **LO** | **DO** | **—** | **—** | **LO** | **DO** | **—** |
| Total Future | Move0  Move1  Move2  Move3  Move4  Move5  Move6  Move7  Move8  Move9  Move10  Move11 | V0  V1  V2  V3  V4  V5  V6  V7  V8  V9  V10  V11 | L0  L1  L2  L3  L4  L5  L6  L7  L8  L9  L10  L11 | D0  D1  D2  D3  D4  D5  D6  D7  D8  D9  D10  D11 | Q0  Q1  Q2  Q3  Q4  Q5  Q6  Q7  Q8  Q9  Q10  Q11 | V0  V1  V2  V3  V4  V5  V6  V7  V8  V9  V10  V11 | L0  L1  L2  L3  L4  L5  L6  L7  L8  L9  L10  L11 | D0  D1  D2  D3  D4  D5  D6  D7  D8  D9  D10  D11 | Q0  Q1  Q2  Q3  Q4  Q5  Q6  Q7  Q8  Q9  Q10  Q11 | V0  V1  V2  V3  V4  V5  V6  V7  V8  V9  V10  V11 | L0  L1  L2  L3  L4  L5  L6  L7  L8  L9  L10  L11 | D0  D1  D2  D3  D4  D5  D6  D7  D8  D9  D10  D11 | Q0  Q1  Q2  Q3  Q4  Q5  Q6  Q7  Q8  Q9  Q10  Q11 |
| **Overall** | **—** | **LO** | **DO** | **—** | **—** | **LO** | **DO** | **—** | **—** | **LO** | **DO** | **—** |

[to be replaced with intersection name by python script]

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